

FIG. 1

200 LIBRARY

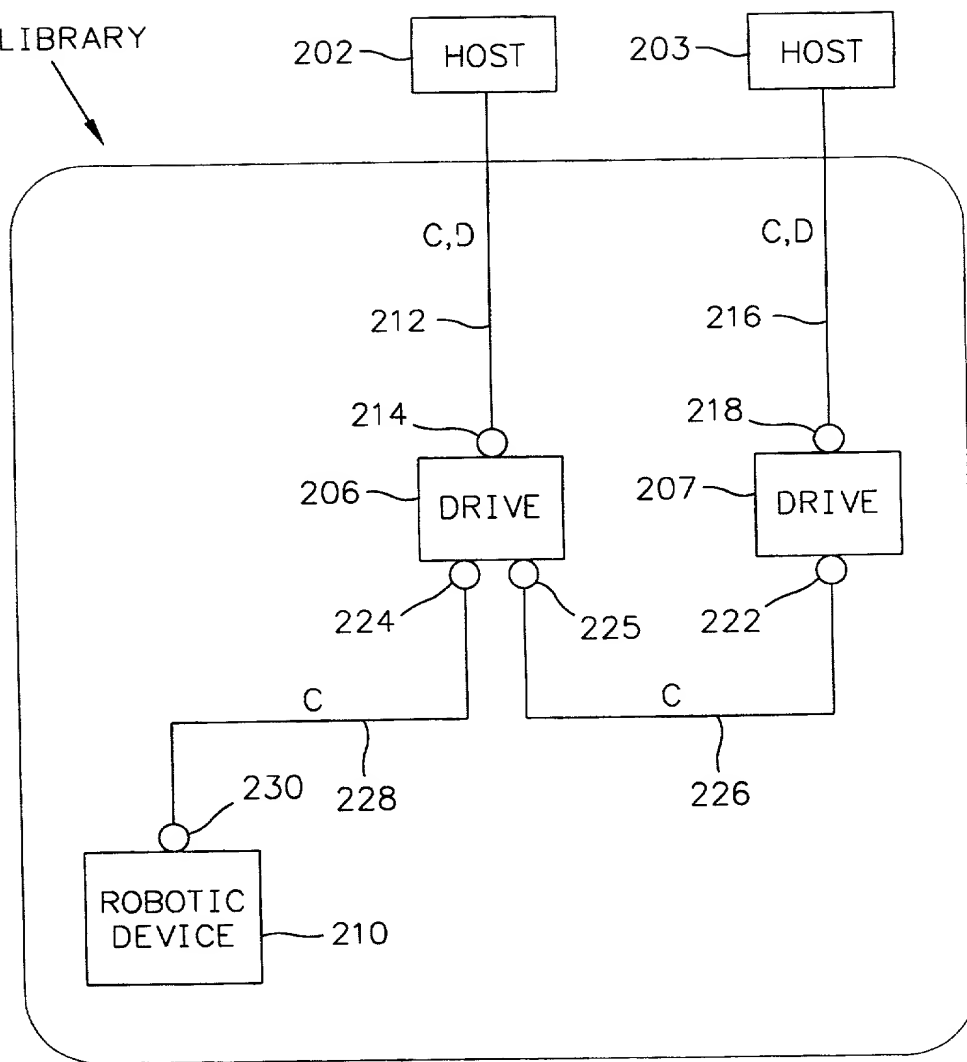


FIG. 2

FIG. 3 is a block diagram of a system 300 for controlling a robotic device 312. The system 300 includes a library 302, a host 303, a host 304, a drive 306, a drive 307, a drive 308, a drive 309, a robotic device 312, and a control unit 310. The library 302 is connected to the host 303 and the host 304. The host 303 is connected to the drive 306. The host 304 is connected to the drive 307. The drive 306 is connected to the drive 307. The drive 307 is connected to the drive 308. The drive 308 is connected to the drive 309. The drive 309 is connected to the robotic device 312. The control unit 310 is connected to the drive 306, the drive 307, the drive 308, and the drive 309.

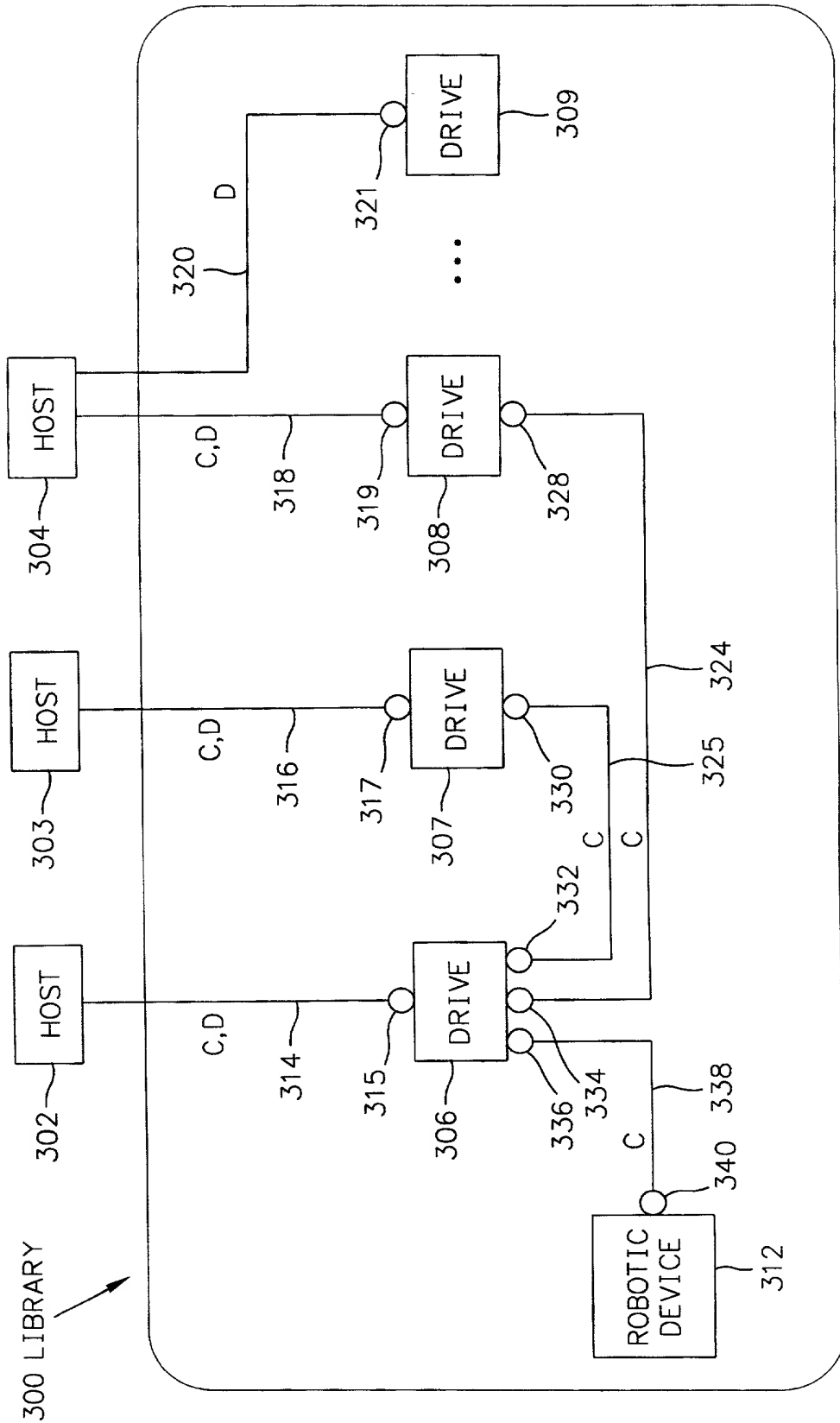


FIG. 3

400 LIBRARY

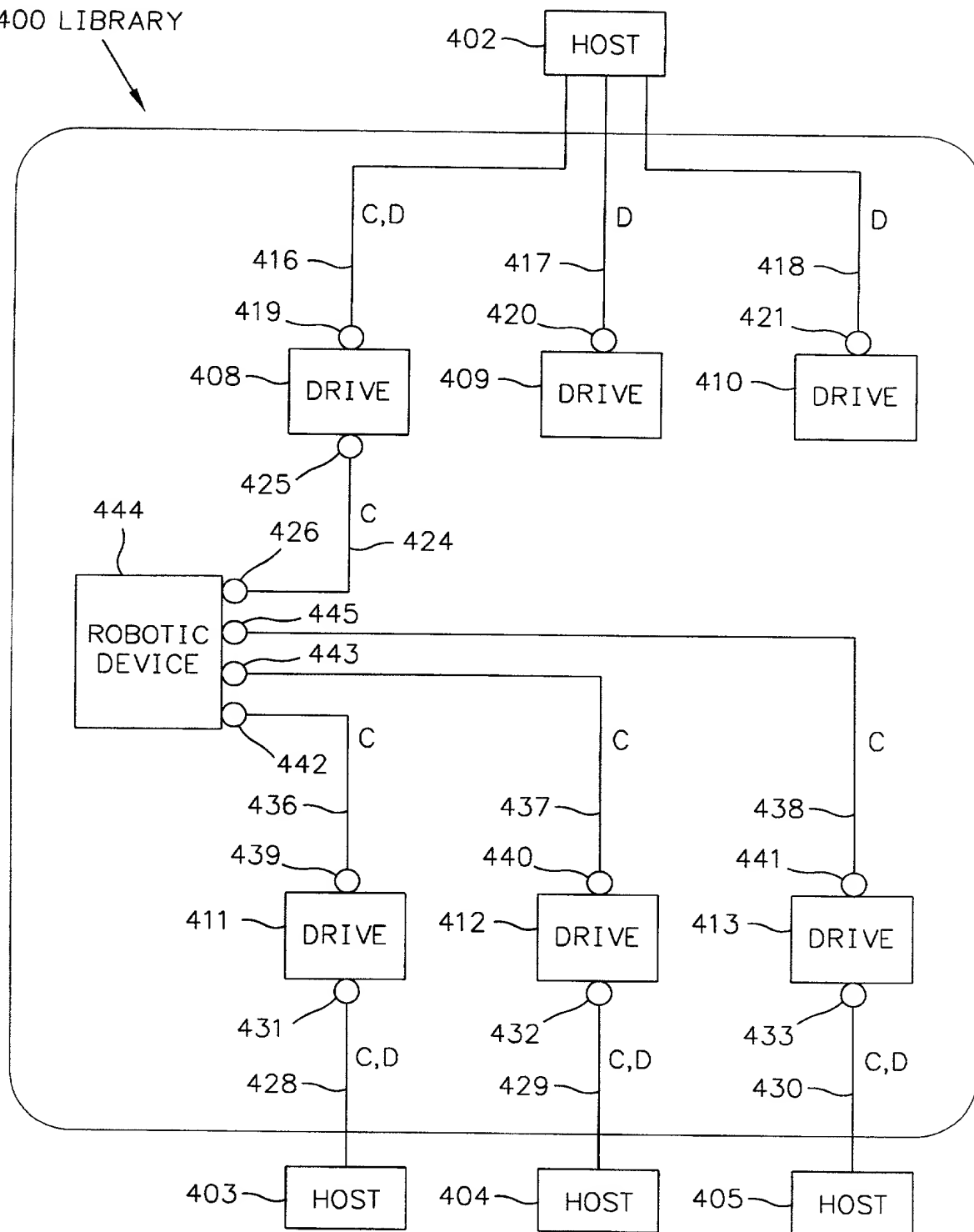


FIG. 4

500 LIBRARY

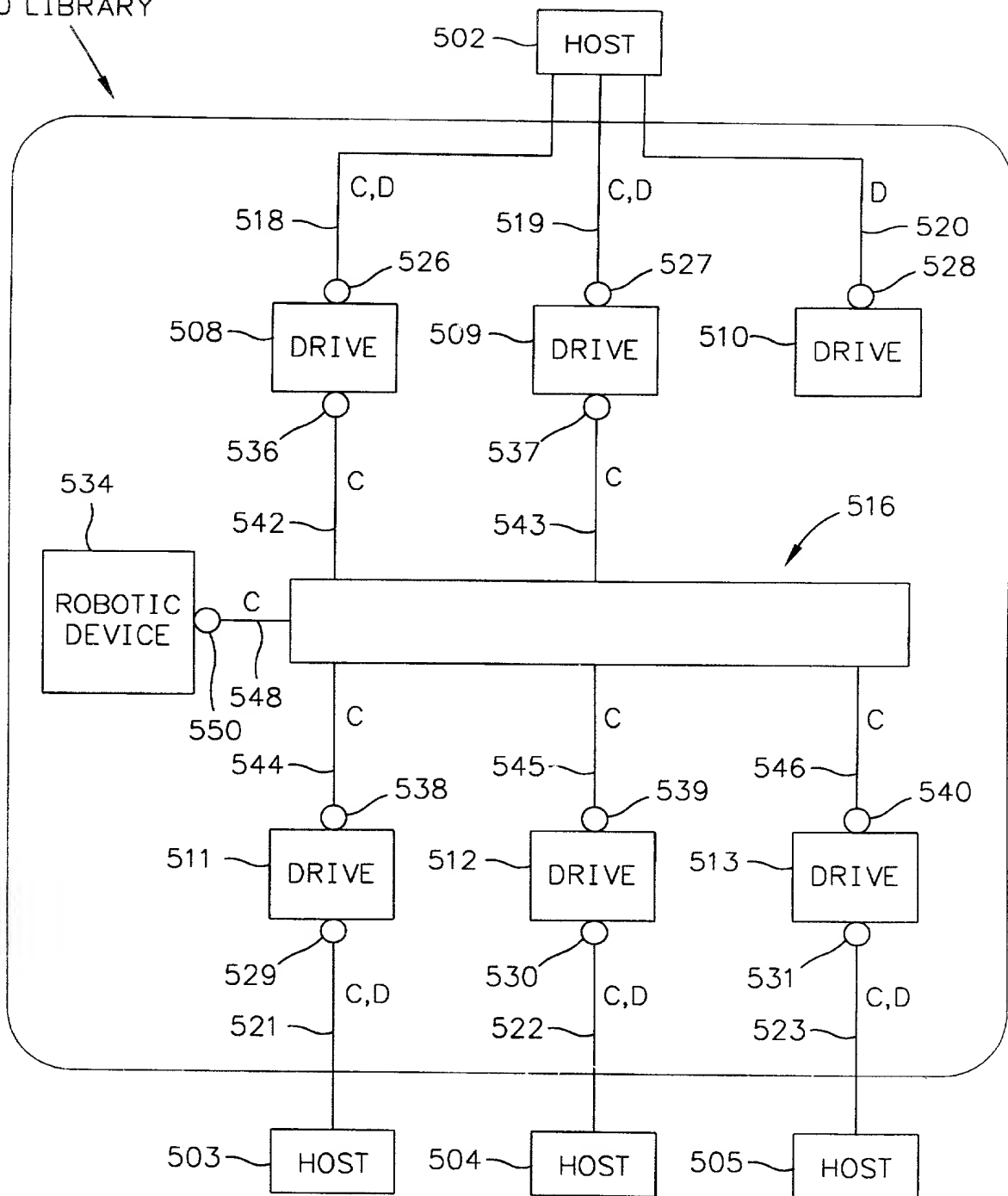


FIG. 5

600 LIBRARY

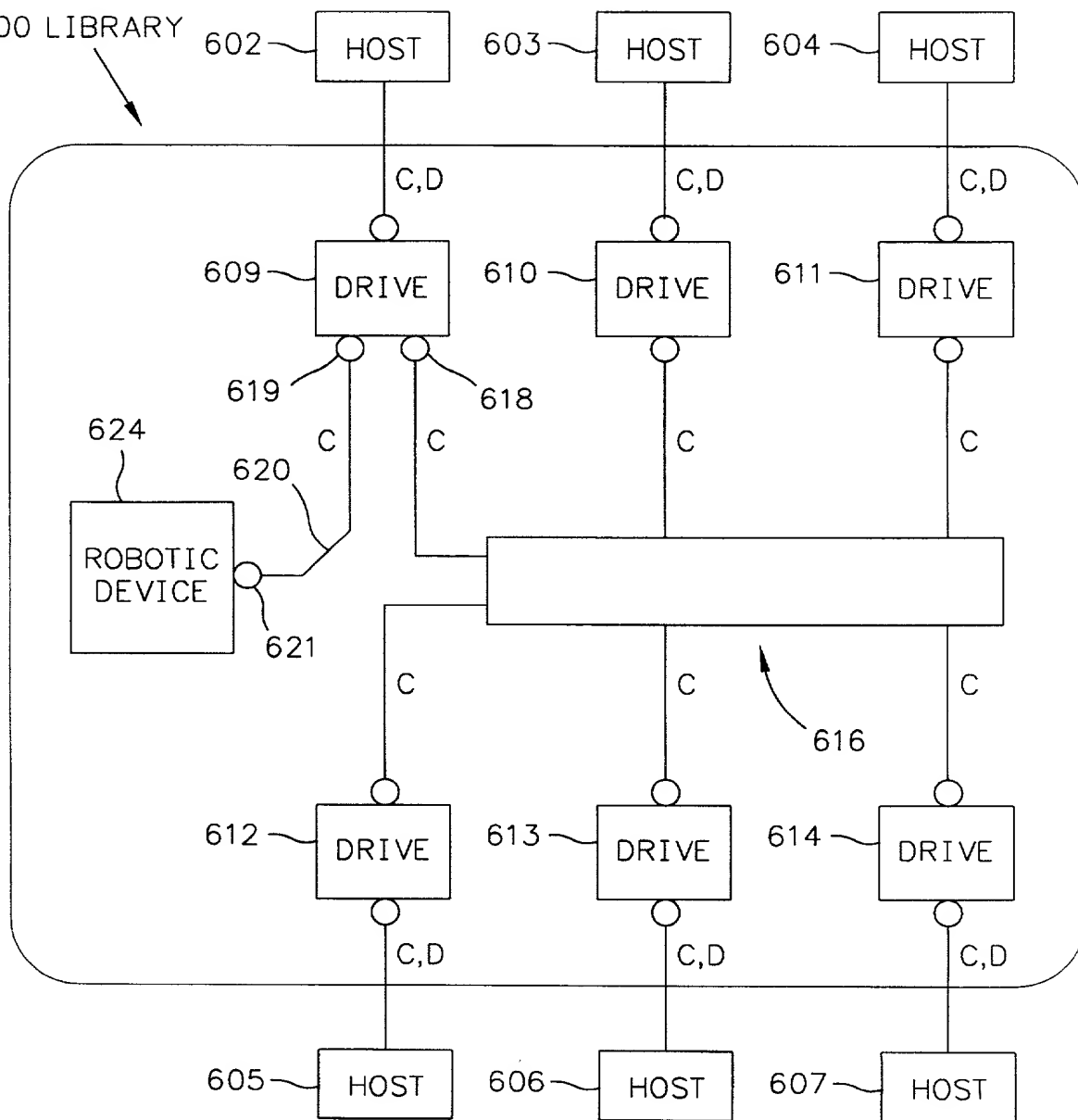


FIG. 6

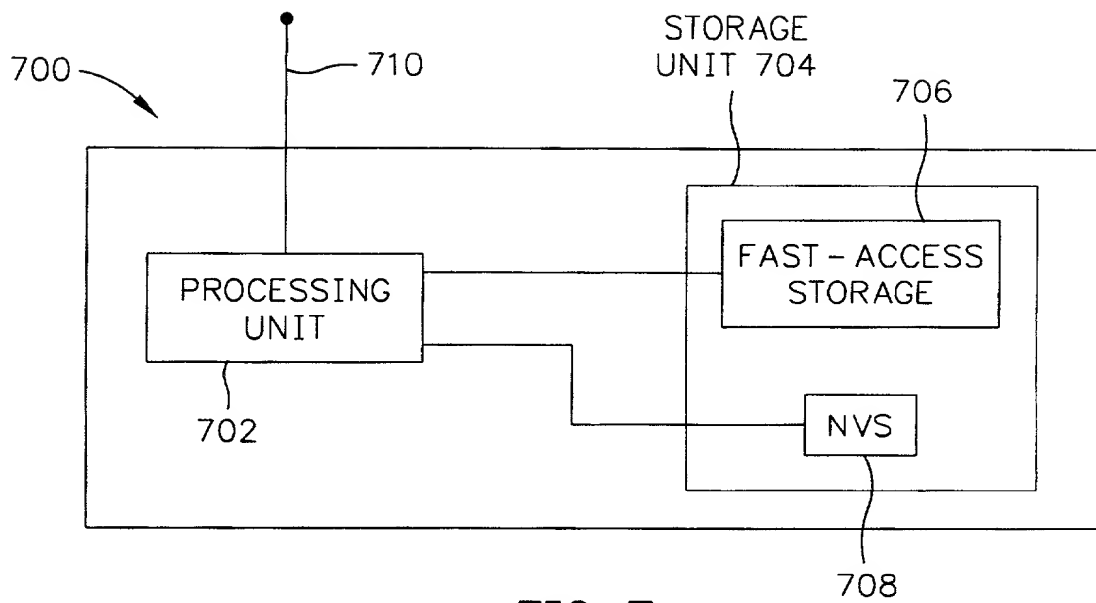


FIG. 7

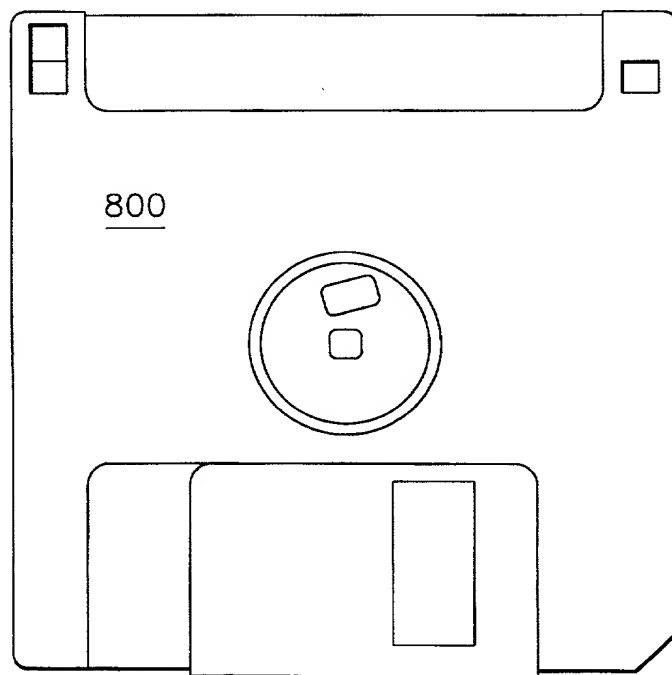


FIG. 8

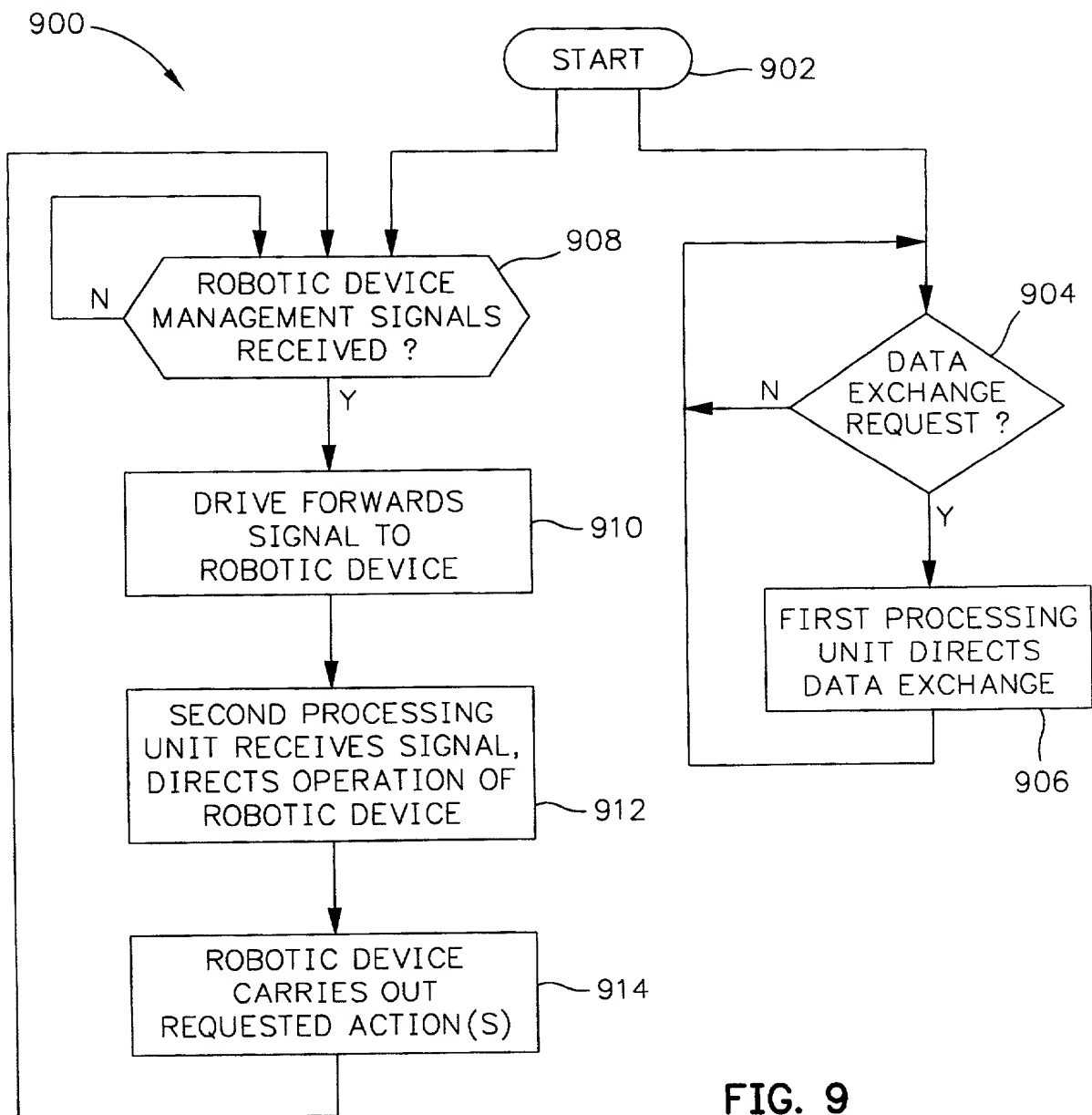


FIG. 9

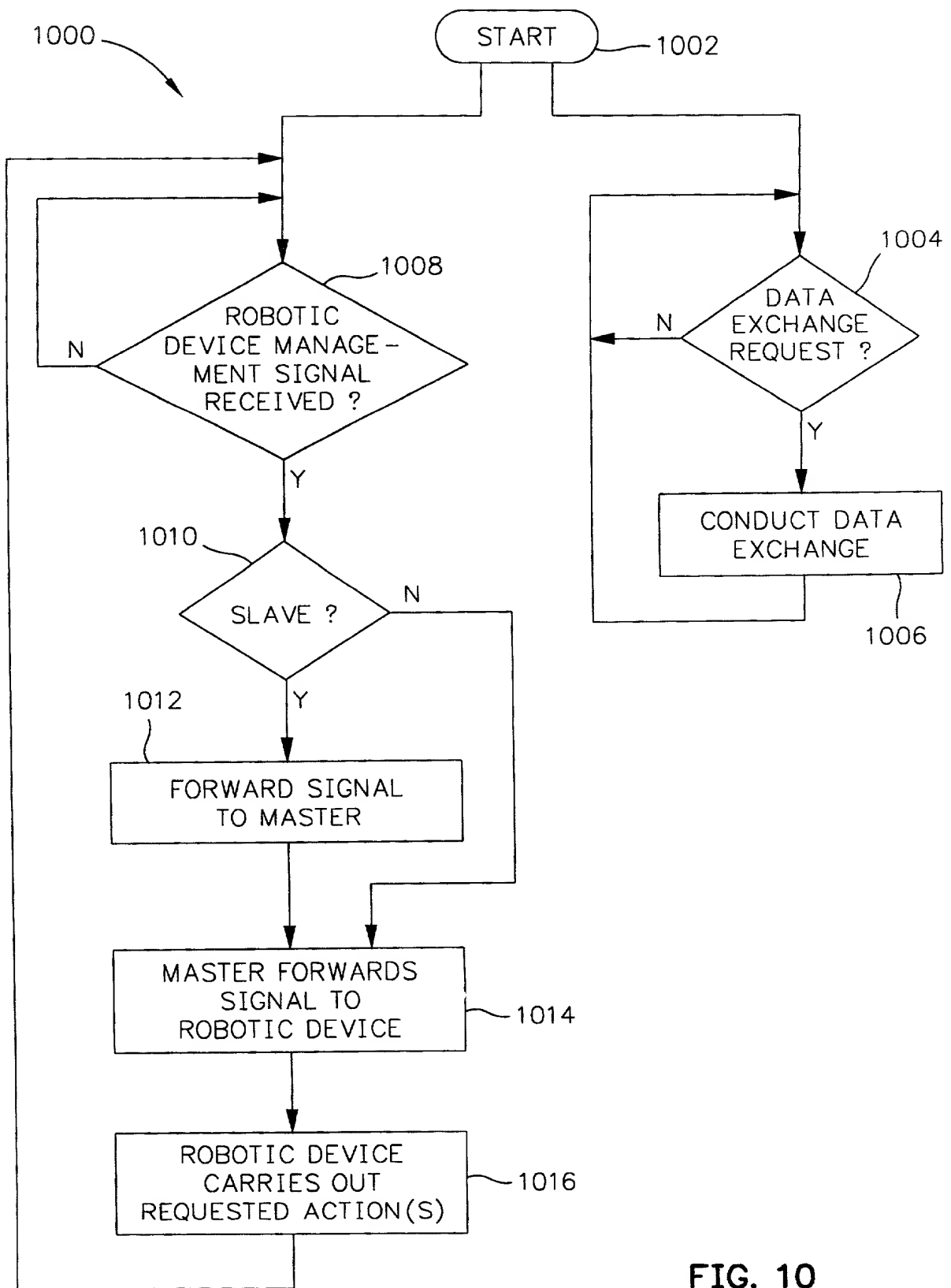


FIG. 10

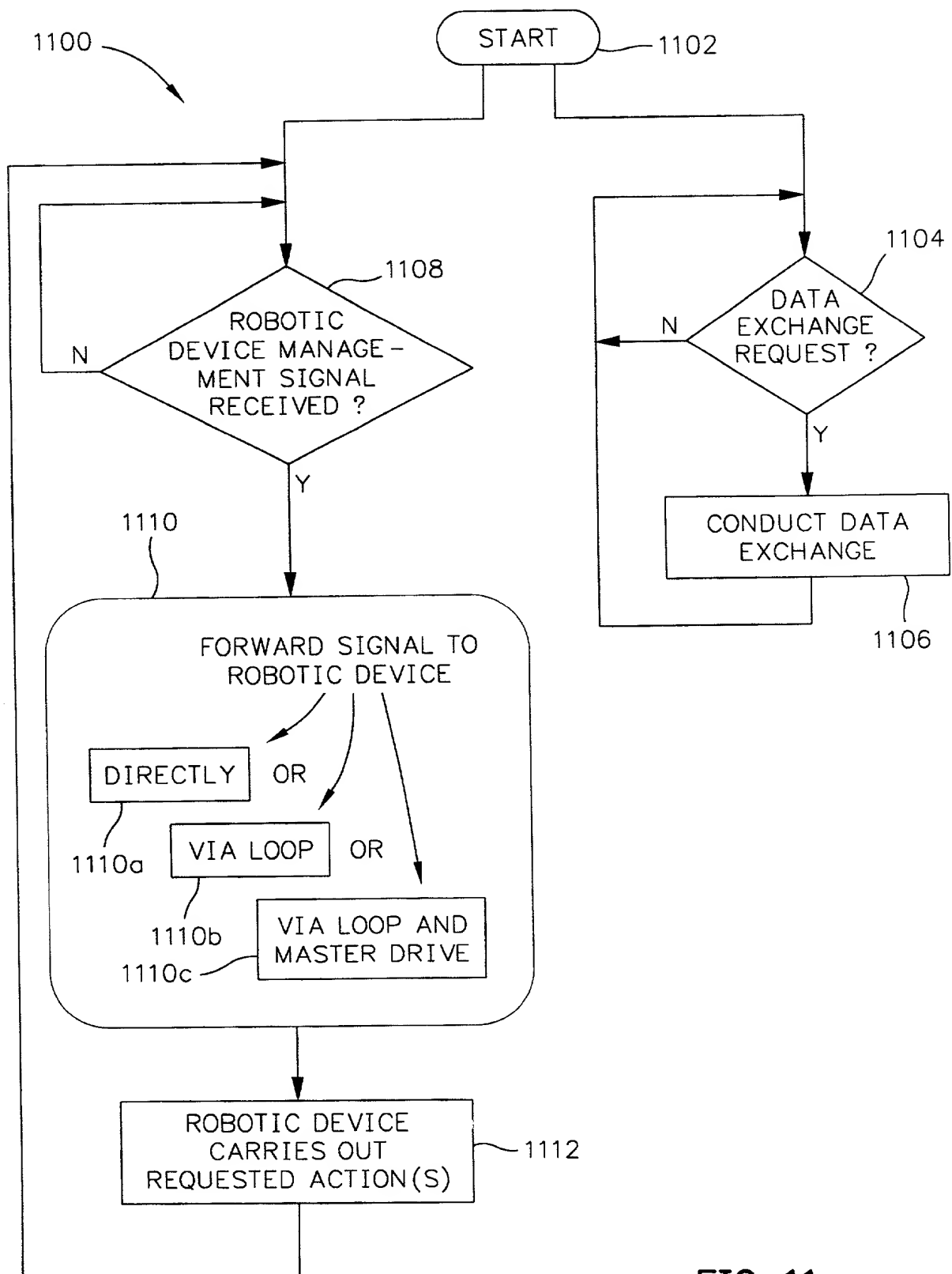


FIG. 11

FIGURE 12

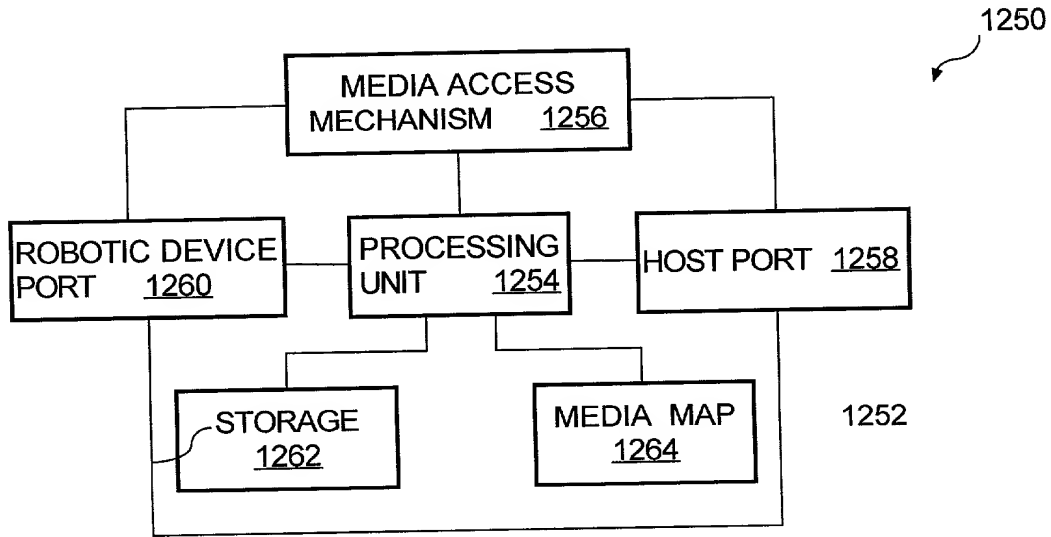


FIGURE 13

